After Ratification: A Causal Mediation Analysis of International Human Rights Treaty

Motivation

- Causal mediation of human rights treaty effect with multiple mediators.
- Roadmap: "define first, identify second, estimate last." Define in counterfactual language, identify in causal graphs, estimate with machine learning-based estimators.
- Varying causal assumptions for identification.
- Parametric regression-based estimator vs. machine learning-based inverse probability of treatment-weighted (IPTW) estimator.

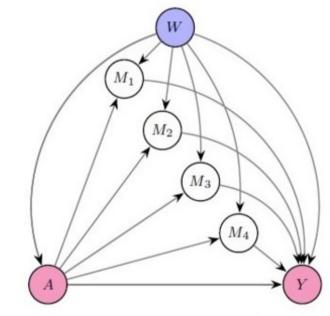
2 Theory

- Treaty ratification influences human rights conditions through multiple causal pathways: – Directly (normative persuasion and emulation).
- Indirectly through (1) domestic electoral accountability; (2) domestic legislative agendasetting; (3) domestic judicial enforcement; (4) international NGOs mobilizing.
- How much does ratification of the Convention against Torture (A) change human rights conditions (Y) directly and indirectly (through M_1 to M_4) given the confounders (W)?

Formulation 3

- Structural and graphical causal models to represent the data-generating process from which *n* observations are independently and identically sampled $O = (W, A, M_1, \ldots, M_4, Y) \sim P_O$.
- Causal quantities: $E[Y_{1,M_1}]$, $E[Y_{0,M_0}]$, and $E[Y_{1,M_0}]$.
- Causal parameters: $TE = E[Y_{1,M_1} Y_{0,M_0}] = E[Y_{1,M_1} Y_{1,M_0}] + E[Y_{1,M_0} Y_{0,M_0}]$

Identification



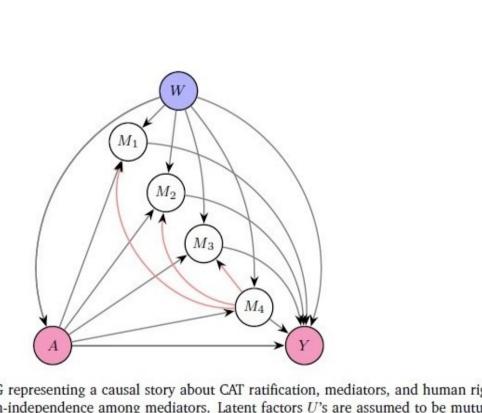


Figure 1: A causal DAG representing a causal story about CAT ratification A, mediators/mechanisms of influence M_1 to M_4 , and human rights outcome Y. Latent factors U's are assumed to be mutually outcomes in case of non-independence among mediators. Latent factors U's are assumed to be mutually independent and are not represented in the causal graph. All mediators are assumed to be conditionally independent and are not represented in the causal graph. Mediators are assumed causal dependent and causally independent. considered as jointly mediating the causal effect of ratification.

- Identification conditions for TE: (1) W_1 leaves open causal paths from A to Y; (2) W_1 blocks backdoor paths from A to Y; (3) W_1 does not create spurious paths involving a collider or a descendant of a collider.
- Additional conditions for NDE and NIE: (1); W_2 blocks backdoor paths from M to Y that do not go through A; (2) W_2 blocks backdoor paths from A to M.
- Separate sets W_1 and W_2 possible more flexible. In practice, one sufficient set W_1 . • Causal independence among mediators: counterfactuals computable from observed condi-
- tional probability.

$$-E[Y_{1,M_1}] = E_W[Y|A=1, W=w]$$

- $-E[Y_{0,M_0}] = E_W[Y|A=0, W=w]$
- $-E[Y_{1,M_0}] = E_{M,W}[Y|A=1, M=m, W=w]P(M=m|A=0, W=w)$
- Causal dependence among mediators: counterfactuals generally non-computable. TE and joint NIE still computable.

Estimation

• Observed joint distribution P_n of n = 3,992 observations from 184 countries (1992 – 2013).

Table 1: Model variables

Sets	Variables and References			
W	 Ratification rules measured by Simmons (2009) Domestic legal traditions (Mitchell, Ring and Spellman 2013) measured by La Porta, Lopez-de Silanes and Shleifer (2008) Electoral rules (Cingranelli and Filippov 2010) measured by Cruz and Scartascini (2016) and Simmons (2009) Treaty Commitment Propensity Lupu (2014) measured by Lupu (2014) Gross domestic product (GDP) per capita (Hafner-Burton and Tsutsui 2007) Participation in international trade (Hafner-Burton 2013) Population size (Hafner-Burton and Tsutsui 2007) Regime types (Hathaway 2007; Chapman and Chaudoin 2013; Neumayer measured by Polity IV (Marshall Monty, Keith and Robert 2016). Regime durability (Goodliffe and Hawkins 2006) measured by Polity IV (Marshall Monty, Keith and Robert 2016). Freedom of the press (Conrad and Moore 2010) measured by Freedom Ho Involvement in international or domestic conflicts (Chapman and Chaudoi measured by Themnér (2014) Region indicators measured by United Nations Regional Groups. 			
A	Ratification of the CAT			
М	 <i>M</i>₁:Electoral accountability (Dai 2005) measured by Government Vote Share (Beck et al. 2001) <i>M</i>₂: Legislative agenda setting (Lupu 2015) measured by Political Constraint Index (Henisz 2002) <i>M</i>₃: Judicial enforcement (Powell and Staton 2009; Conrad 2013) measure Latent Judicial Independence (Linzer and Staton 2015) or by the Rule of Law measure (Kaufmann, Kraay and Mastruzzi 2011) <i>M</i>₄: Mobilization (Murdie and Davis 2012; Simmons 2009) measured by International Non-governmental Organizations from (Lupu 2015) 			
Y	Human Rights Protection Scores (Fariss 2014)			

Figure 1: Model variables

- Linear models of outcome and mediators (joint mediators with causal dependence) using bootstrap-based inference and linear models (individual mediators with causal independence) using simulation-based inference.
- Estimates are statistically insignificant and non-distinguishable from zero.

Table 2: Causal mediated effects of CAT ratification estimated using linear parametric models with boot- Table 3: Natural indirect effects of CAT ratification estimated using linear parametric models with strap SE.

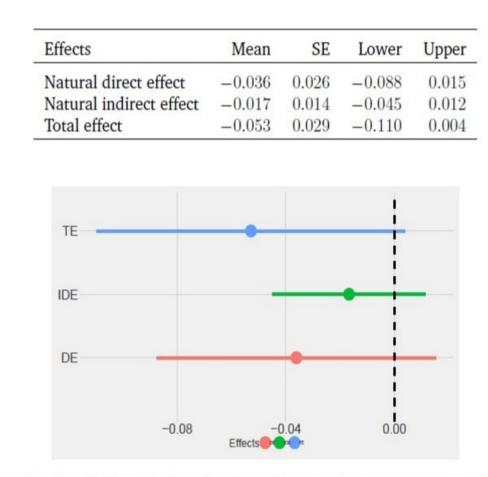


Figure 3: Causal mediated effects of CAT ratification on human rights outcome measured in Human Rights Scores (0 – 1 scale), 1992 – 2013. All mediators are considered jointly, that is, they simultaneously take on their natural values under either ratification or non-ratification

- Parametric models vs. machine learning algorithms: unknown true predictive function Y = f(A, M, W); least square loss function $E[Y - Q(A, M, W)]^2$.
- Parametric models fare worse. Super Learner has the best performance, more closely approximating the true function. Flexible tools exist (e.g., mediation package), but still require parametric specification. Super Learner automates choices with better performance.

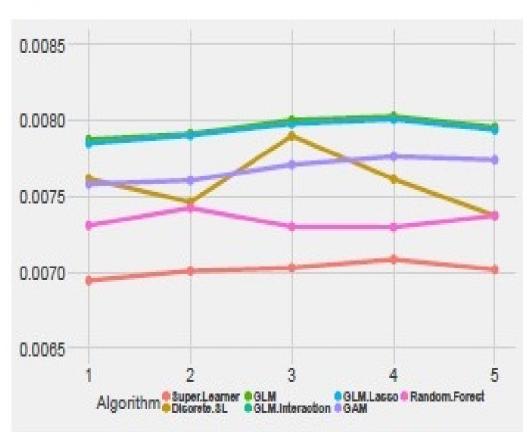
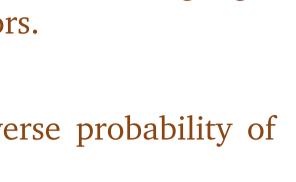


Figure 5: 20-fold cross-validated average risk estimates of predicting human rights outcome (measured in Human Rights Scores on 0 - 1 scale, 1992 - 2013) by seven algorithms (Ensemble Super Learner, Discrete Super Learner, Random Forest, GAM, GLM Lasso, GLM) across five imputed datasets. Cross-validated risks for GLM with two-way interaction are so high they have to be cropped out of Figure 5 for ease of presentation.



$$Y_{0,M_0}] = \text{NIE} + \text{NDE}$$

lman 2013) measured by easured by sured by Lupu (2014) Burton and Tsutsui 2007) 12013)audoin 2013; Neumayer 2007) and Robert 2016). and Robert 2016). easured by Freedom House Chapman and Chaudoin 2013) tional Groups. Dy ured by 9; Conrad 2013) measured by aton 2015) or

simulation-based SE. Mediators are considered individually and successively

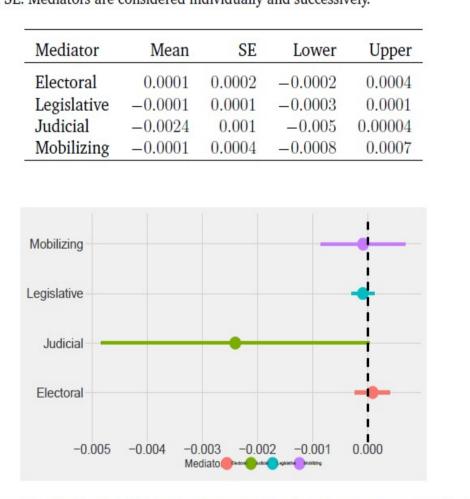


Figure 4: Causal mediated effects of CAT ratification on human rights outcome measured in Human Rights Scores (0 – 1 scale), 1992 – 2013. All mediators are considered individually and successively.

- uses stabilized weights.
- stabilized weights $\frac{P(A=1)}{P(A=1|W)}$ and $\frac{P(A=0)}{P(A=0|W)}$, respectively.
- Super Learner-predicted stabilized weights $\frac{P(A=1)}{P(A=1|W)}$.
- ators. Unable to tease out portion mediated by individual mediators.
- significant.



some hint about the effectiveness of the legislative mechanism.

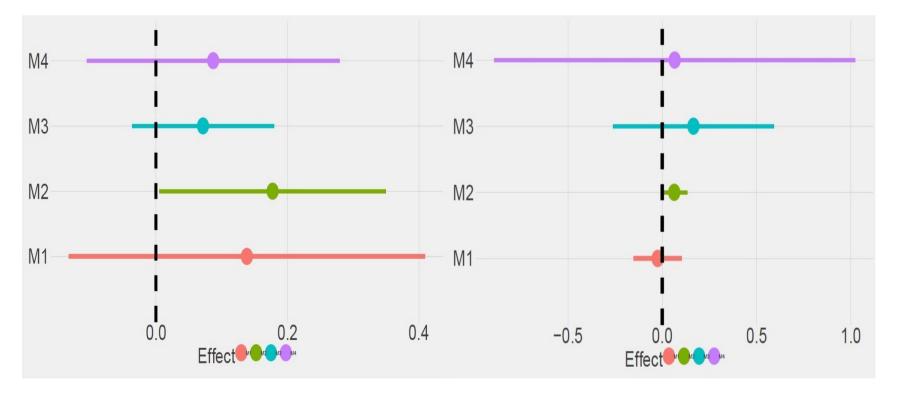


Figure 2: Left: causal effect of A on each M (M on 0 - 1 scale). Right: causal effect of each M dichotomized at empirical mean on Y (Y on 0-1 scale). M1: electoral mechanism; M2: legislative mechanism; M3: judicial mechanism; M4: international NGOs mobilizing. Identification based on causal graphs with causal dependence among mediators. Estimation uses Super Learner-based targeted maximum likelihood estimation.

Conclusion 6

- tional human rights research.
- research could be especially fruitful.

Sinh Nguyen

Purdue University Department of Political Science Email: nguyens@purdue.edu

• Super Learner-based IPTW: (1) avoids modeling multiple (continuous) mediators, less computationally expensive; (2) uses Super Learner to predict weights and outcome values; (3)

- Compute $E[Y_{1,M_1}] = E_W[Y|A = 1, W = w]$ and $E[Y_{0,M_0}] = E_W[Y|A = 0, W = w]$: mean outcome values among observations with A = 1 and A = 0 and given SL-predicted

-Compute $E[Y_{1,M_0}] = E_{M,W}[Y|A = 1, M = m, W = w]P(M = m|A = 0, W = w)$:

mean Super Learner-predicted outcome values among observations with A = 0 (using their corresponding values of mediators), but fix treatment value at A = 1 and then given

- Assumption of causal dependence among mediators only permits joint modeling of medi-

– Natural direct effect and (joint) natural indirect effect both statistically and substantively

Table 6: Super Learner-based estimates of natural direct and indirect effects of CAT ratification on human rights outcome (measured in Human Rights Protection Scores on a 0 - 1 scale, 1992 - 2013)

SE	Lower	Upper	Effects
0.158	0.007	0.145	0.171
0.113	0.002	0.109	0.116
0.045	0.008	0.029	0.061

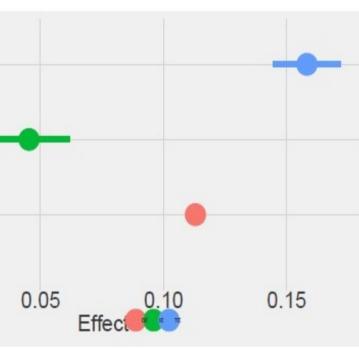


Figure 6: Super Learner-based estimates of natural direct and indirect effects of CAT ratification

• Informally, $E[Y_{1,M_1}] - E[Y_{1,M_0}]$ is about how much a change in mediator due to a change in treatment will impact the outcome. E[M|do(A = 1)] - E[M|do(A = 0)], causal effect of A on each M, and E[Y|do(M = 1)] - E[Y|do(M = 0)], causal effect of each M on Y, might give

• Further empirical analyses are needed to keep up with theoretical developments in interna-

• Positive impact by treaty ratification, both directly and indirectly; particularly the direct effect of normative persuasion and possibly the indirect effect through legislative mechanism.

• Combination of recent developments in causal inference literature and machine learning